

# Lithium-Ion HE battery module

# - Manual -

MGHE240100, MGHE241100, MGHE242100 (HE 100Ah) MGHE240150, MGHE241150, MGHE242150 (HE 150Ah) MGHE240200, MGHE241200, MGHE242200 (HE 200Ah) MGHE240300, MGHE241300, MGHE242300 (HE 300Ah)

Also applicable to older series HP and UHE

MG Energy Systems B.V.





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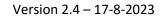
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# 1 GENERAL

Before continuing read the instructions in this chapter carefully and be sure the instructions are fully understood. If there are questions after reading the instructions please consult MG Energy Systems.

# 1.1 Document history

 Table 1 - Document history

Rev.	Date	Changes	<b>Revision author</b>
2.0	13-01-2019	Initial document.	Mark Scholten
2.1	24-11-2020	Major changes: Text, images, added new chapters etc.	Mark Scholten
2.2	11-01-2020	<ul> <li>Update schematic in Figure 1. Fixed minor typos.</li> <li>Removed image on page 27. This was not intended to be there.</li> </ul>	Mark Scholten
	26-08-2021	Updated battery designation in section 5.1.4.	Frank van Son
2.3	21-09-2022	<ul> <li>Updated images</li> <li>Extended storage notes text in chapter 3.2.</li> <li>Changed voltage levels and number of battery modules in series to 144V and 6 modules in series.</li> <li>Added chapter risk assessment to chapter 2.2.3.</li> <li>Added "Other labels" to chapter 5.2.</li> <li>Updated dummy fuse article number in chapter 6.2.3.1.</li> <li>Removed 2C heat rejection from chapter 7.2.2.1.</li> <li>Added chapter 7.3.1 Placement in battery box.</li> <li>Changed float voltage to 28,0 V in chapter 7.4.6.1.</li> <li>Added chapter 8.1 Tooling.</li> <li>Updated connection of positive and negative power cables and CAN-Bus connections.</li> <li>Extended the commissioning in chapter 9.</li> <li>Extended the maintenance in chapter 10.</li> <li>Changed "Dummy fuse" to non-fused battery pole in the complete document</li> </ul>	Mark Scholten
2.4	17-08-2023	<ul> <li>Added the battery box link</li> <li>Minor changes and typo fixes</li> </ul>	Wiard Jansma

# 1.2 Terms, abbreviations, and definition

Table 2 - Terms, abbreviations, and definitions

Battery cell	<i>Battery cell;</i> the smallest building block in a battery, a chemical unit. Cell is the bare Lithium-Ion battery cell.
Battery module	<i>Battery module;</i> is an assembly of submodules, BMS and outer enclosure.
Battery stack	<i>Battery stack;</i> is a set of multiple cells in cell cassettes constructed as one.
BMS	<i>Battery Management System;</i> The BMS is the electronics that monitors the battery cell parameters to keep it within the operation specifications.

CAN-bus	Controller Area Network bus; CAN-bus is a standard serial data-bus
	that provides data communication between two or more devices.
C-rate	<i>C-Rate;</i> the current (A) used to charge/discharge the battery system
Chale	
	divided by the rated ampere-hours (Ah).
EMS	Energy Management System; The EMS controls all power sources
	and consumers in a system.
HVIL	High Voltage Interlock Loop; is a wire loop which is created for
	protection of pulling cables from the battery system while in
	operation. It shuts down the system when loop is not closed.
IC	Integrated Circuit; is a chip containing an electronics circuit;
MSDS	Material Safety Data Sheet; is a document that lists information
	relating to occupational safety and health for the use of various
	substances and products.
NMEA 2000	National Marine Electronics Association's NMEA 2000 is a plug-and-
	play communications standard used for connecting marine sensors
	and display units within ships and boats, standardised in the IEC
	61162-1.
РСВ	Printed Circuit Board; is a board containing an electronic circuit;
РСВА	Printed Circuit Board Assembly; is a board containing an electronic
	circuit including passive and active components;
SoC	<i>State-of-Charge;</i> is the remaining capacity in a battery cell or module
	in percent (%).
SoH	State-of-Health; is a figure of merit of the condition of a battery (or a
	cell, or a battery pack), compared to its ideal conditions.



# **2** SAFETY INSTRUCTIONS

Follow the safety instructions in this document to ensure your own safety.

# 2.1 Safety message level definition

Table 3 - Safety message levels overview



### WARNING:

A hazardous situation which, if not avoided, could result in death or serious injury.



### CAUTION:

A hazardous situation which, if not avoided, could result in minor or moderate injury.



### LIMITATION:

A limitation to use which must be considered for safe use of the equipment.



### ELECTRICAL HAZARD:

The possibility of electrical risks if instructions are not followed in a proper manner.

### NOTICE:

- A potential situation which, if not avoided, could result in an undesirable result or state.
  - A practice not related to personal injury.

# 2.2 User health and safety

This product is designed and tested in accordance with international standards. The equipment should be used according the intended use only.



### WARNING:

A battery is a permanent energy source which cannot be turned off.

### **ELECTRICAL HAZARD:**

- Wear applicable personal protective equipment when working on a battery system.
- Use insulated tools when working on a battery system.
- Make sure the local health and safety regulations for working on battery systems are followed.
- There is a risk of electrocution and burns when working on higher voltage systems without proper protective gear and special training.



### 2.2.1 Qualifications and training

The personnel responsible for the assembly, operation, inspection, and maintenance of the battery system must be appropriately qualified. The user company must do the following tasks:

- Define the responsibilities and competency of all personnel working on the battery system.
- Provide instruction and training.
- Ensure that the contents of the operating and safety instructions have been fully understood by the personnel.
- Check the local safety rules and guidelines they have higher preference over the manufacturers specification in case of regulatory conflicts.
- Working on higher voltages requires specific training and certification.

Instructions and training can be carried out by MG Energy Systems B.V. by order of the user company.

### 2.2.2 Non-compliance risks

Failure to comply with all safety precautions can result in the following conditions:

- Death or serious injury due to electrical, mechanical, and chemical influences.
- Environmental damage due to the leakage of dangerous materials.
- Product damage.
- Property damage.
- Loss of all claims for damages.

### 2.2.3 Risk assessment

For every integration of the battery system it is mandatory to perform a risk assessment.

Goal of the risk assessment is to identify the hazards and determine the corresponding risks for the particular application.

The following topics need to be addressed:

- Fire hazards (fire from the batteries, fire from external source etc.)
- Environmental hazards (moisture, water ingress, vibration, heat etc.)
- Electrical hazards (short-circuit, cable dimensioning, cable routing etc.)
- Installation and operational hazards (lifting, communication, power loss etc.)

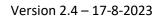
### 2.2.4 Unacceptable modes of operation

The operational reliability of this product is only guaranteed when it is used as intended. The operating limits on the identification tag and in the data sheet may not be exceeded under any circumstances. If the identification tag is missing or worn, contact MG Energy Systems B.V. for specific instructions.



### WARNING:

The battery modules may only be used in combination with a master BMS. (<u>MG Master LV</u> or <u>MG Master HV</u>)





# **3** TRANSPORT, STORAGE, UNPACKING AND HANDLING

# 3.1 Transport

The package and transport instructions provided by the manufacturer must be followed under all circumstances.

Notes on transport:

- Use original packaging materials.
- Lithium-Ion batteries are dangerous goods and must be transported according to the applicable rules.
- Transportation company and shipper must be qualified to transport and package dangerous goods.
- The SoC during transport must be  $\leq$  30%.



For details on transport of this battery module see the MSDS and general transport instructions.



### CAUTION:

It is not allowed to transport, connect or operate a damaged battery.



# NOTICE:

No liability can be accepted for damage during transport if the equipment is not transported in its original packaging or if the original packaging is opened before the destination is reached.



### NOTICE:

The SoC of the battery as delivered from factory is  $\leq$  30%.

# 3.2 Storage

The storage instructions provided by the manufacturer must be followed in all circumstances.

Notes on storage:

- Battery module must be stored in its original packaging.
- Store in a dry, clean, and conditioned location.
- Local regulations for storage of dangerous goods may be applicable.
- Recommended storage temperature of the battery module is between +10°C to +25°C.
- It is recommended to limit the battery charge between 50% and 70% SoC. This will limit calendric aging.

The battery module's SoC is decreasing 1% per year when not connected to any equipment, including MG Master LV or MG Master HV. Recharging is required when the voltage is in the range of the cut-off voltage.



# NOTICE:

Check the MG Master LV or MG Master HV manual for storage of a connected system.



## NOTICE:

Check the voltage of the stored battery module every year. When the battery module voltage is < 24 VDC, recharging is required. Contact MG Energy Systems for specific instructions and tools.

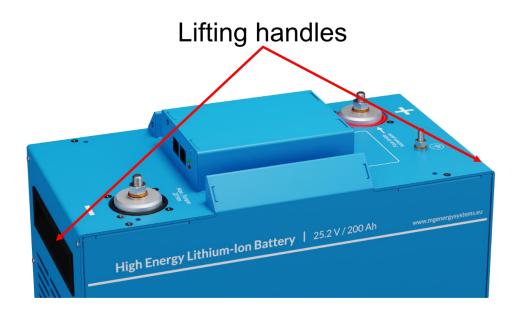
# 3.3 Unpacking and handling

Follow these handling guidelines when handling the product to prevent damage during unpacking:

- Use care when handling the product.
- Leave protective caps and covers on the product until installation.

### 3.3.1 Lifting the battery module

Use the handles on the side of the battery module for lifting:





### CAUTION:

**CAUTION:** 

Always take the local applicable standards and regulations regarding the prevention of accidents into account when handling the product.



Be aware of the total mass of the product and do not lift heavy objects unassisted.



### 3.3.2 Scope of delivery

The scope of delivery is as following:

NOTICE:

- <u>MG HE battery module</u> of type as described in chapter 5.
- Quick installation guide: <u>HE 100-150-200</u> and <u>HE300</u>
- Top ingress protection cover HE Series (article number: MG4000267)
- Non-fused battery pole (article number: MG4000034).

# (i)

Not within the scope of delivery:

- Power cables and connectors (details can be found in chapter 6.2.3).
- Communication cables and connectors (details can be found in chapter 6.2).



# **4 GENERAL DESCRIPTION**

The HE battery series is based on a high energy density Lithium-Ion NMC battery cell. This means more energy in less weight. The integrated battery management system brings the highest standard on safety and gives insight in the status of the battery. Flexibility in system configuration is created by a modular design. On a system level voltages up to 144 V and capacity up to 720 kWh can be created.

All relevant information of this product can be found on the MG Download Center.

# 4.1 Battery system components

MG Energy Systems Lithium-Ion battery system consists of the following components:

- One or more <u>MG HE battery modules</u> of the same type;
- One <u>MG Master LV</u> or <u>MG Master HV</u> battery management system; Details of these battery management controllers can be found in their separate description documents;
- <u>MG Energy Monitor</u> (optional);
- <u>MG SmartLink MX</u> for parallel redundant control (optional);

# 4.2 Functional description

MG's system philosophy is to have one master BMS, e.g. a MG Master LV or MG Master HV, per bank of battery modules which communicates with one or more slave BMSs integrated in the Lithium-Ion battery module(s). The slave BMSs are monitoring the battery cell parameters like cell voltage and cell temperature. Besides monitoring, the slave BMS also controls balancing of cells based on the input of the master BMS.

All these parameters are send to the MG Master LV or MG Master HV via a dedicated CAN-bus which collects all the data and monitors these parameters with different thresholds. When a parameter exceeds the threshold this will first be communicated to the user via the, separated, auxiliary CAN-bus or the I/O connections. If the exceeded threshold stays, the master BMS has the possibility to disconnect the batteries from the system by opening the main contactors.

Functional and safety features of the MG HE battery module are:

- Superior energy density;
- Modular design;
- Plug and Play installation: Automatic series and parallel detection;
- Low voltage solutions: 24 V up to 96 V;
- High voltage solutions: Up to 144 V;
- RJ45 or M12 CAN-Bus connector options;



# 4.3 Example systems

Different kind of battery system configurations can be created because of the modular design. Battery modules can be placed in series and parallel to create higher voltages and larger capacities.

### 4.3.1 Low voltage systems

Low voltage systems up to 96 VDC are setup with the MG Master LV series. For more information about the MG Master LV, please refer to the data sheet and manual. The example in Figure 1 is a simplified schematic which is not showing all the details.

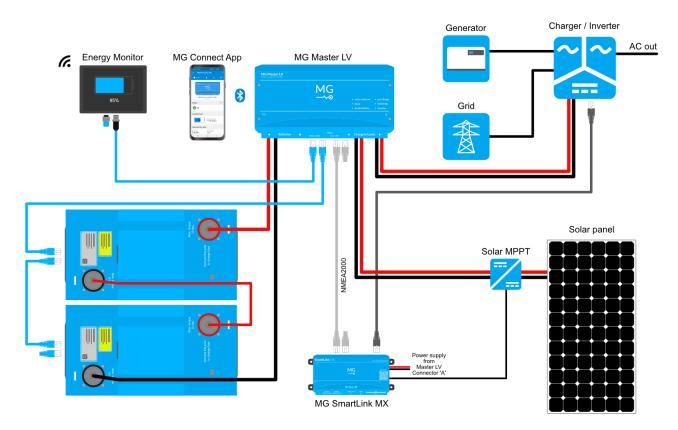
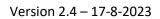


Figure 1 – Example 24 V Marine energy system





### 4.3.2 High voltage systems

High voltage systems up to 144 VDC are setup with the MG Master HV series. For more information about the MG Master HV, please refer to the data sheet and manual. The example in Figure 2 is a simplified schematic which is not showing all the details.

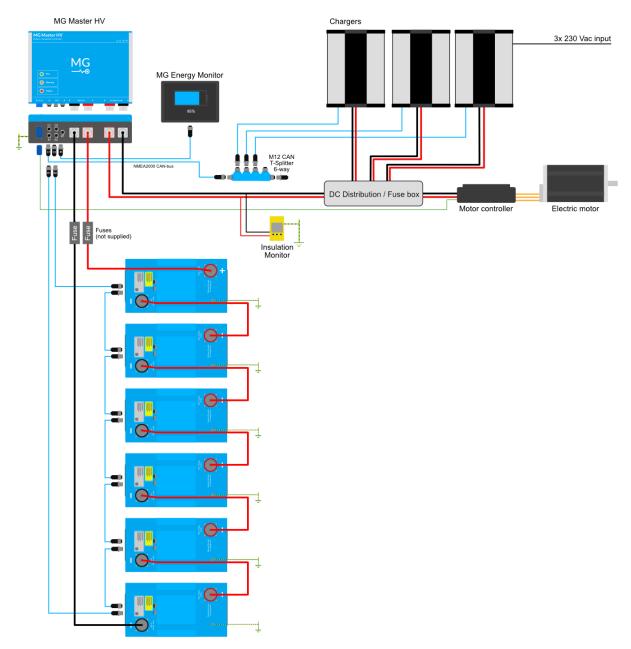


Figure 2 – Example 144 VDC propulsion system



# 5 MODELS

The HE Series has different models and configurations available. The main differences are battery module capacity, maximum system voltage and CAN-Bus connector types.

### 5.1 Models and configurations

Table 4, Table 5 and Table 6 lists the available battery module configurations.

### 5.1.1 RJ45 connectors and systems up to 96 V

Table 4 - Battery module configurations – RJ45 connectors and systems up to 96 V

Article number	MGHE240100	MGHE240150	MGHE240200	MGHE240300
Cell configuration	7S32P	7S48P	7S64P	7S96P
Nr. of cells	224	336 448		672
Nominal voltage	25.2 V			
Capacity	100 Ah	150 Ah	200 Ah	300 Ah
Energy capacity	2.5 kWh	3.7 kWh	5.0 kWh	7.5 kWh

### 5.1.2 M12 connectors and systems up to 96 V

Table 5 - Battery module configurations – M12 connectors and systems up to 96 V

Article number	MGHE241100	MGHE241150	MGHE241200	MGHE241300
Cell configuration	7S32P	7S48P	7S64P	7S96P
Nr. of cells	224	336 448		672
Nominal voltage	25.2 V			
Capacity	100 Ah	150 Ah	200 Ah	300 Ah
Energy capacity	2.5 kWh	3.7 kWh	5.0 kWh	7.5 kWh

### 5.1.3 M12 connectors and systems up to 144 V systems (M12-HV)

Table 6 - Battery module configurations – M12 connectors and systems up to 144 V systems

Article number	MGHE242100	MGHE242150	MGHE242200	MGHE242300
Cell configuration	7S32P	7S48P	7S64P	7S96P
Nr. of cells	224	336 448		672
Nominal voltage	25.2 V			
Capacity	100 Ah	150 Ah	200 Ah	300 Ah
Energy capacity	2.5 kWh	3.7 kWh	5.0 kWh	7.5 kWh



# 5.1.4 Battery designation

As per IEC 62620 it is required to state a standard designation per battery module configuration. For the HE series lithium-ion battery these are given in table 7.

 Table 7 - Battery module designation as per IEC 62620

Article number	Designation
MGHE240100, MGHE241100, MGHE242100 (HE 100Ah)	INR/19/65/[32P7S]E/-10NA/90
MGHE240150, MGHE241150, MGHE242150 (HE 150Ah)	INR/19/65/[48P7S]E/-10NA/90
MGHE240200, MGHE241200, MGHE242200 (HE 200Ah)	INR/19/65/[64P7S]E/-10NA/90
MGHE240300, MGHE241300, MGHE242300 (HE 300Ah)	INR/19/65/[96P7S]E/-10NA/90



# 5.2 Identification label

The identification label of the MG HE battery module is located at the top of the enclosure under the lid.

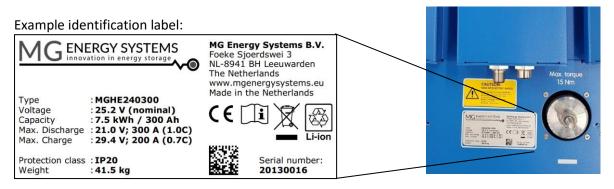


Figure 3 - Example identifications label

The identifications label shown in figure 3 contains written information about the product. The explanation of the symbols used on the identification label is stated in table 8.

Table 8 - Identification lable logo explaination

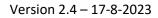
C€	Declaration of conformity with health, safety, and environmental protection standards for products sold within the European Economic Area as per directive 2014/35/EU.
	Symbol indication the manual must be red before installation and use of the device.
X	Device is treated according the Waste Electrical and Electronic Equipment (WEEE) Directive 2012/19/EU.
	GS1 data matrix type barcode containing detailed product information.

### 5.2.1 Other labels

Figure 4 shows the additional labels on the battery module.



Figure 4 - Additional warning and informational labels





# 5.3 Approvals and standards

The HE battery conforms to an extensive list of standards and tests.

- Declaration of Conformity
- Material safety datasheet
- UN38.3 certificate

A complete list of all performed tests can be found at the following link: <u>HE List of Standards and Tests</u>





# **6 OVERVIEW**

This chapter shows an overview of the HE battery.

Each battery module contains the following common parts:

- Negative battery pole connection;
- Positive battery pole connection;
- BMS CAN-bus connection, either RJ45 or M12;
- Status LEDs;

# 6.1 Connection overview

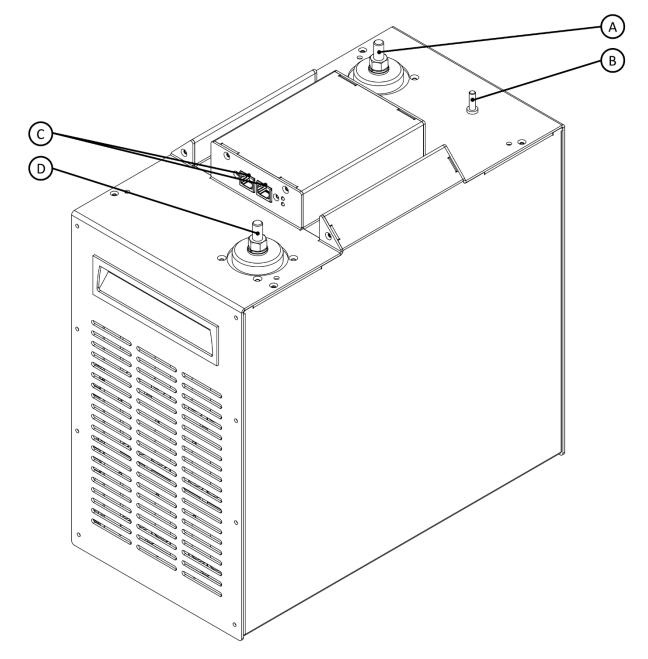
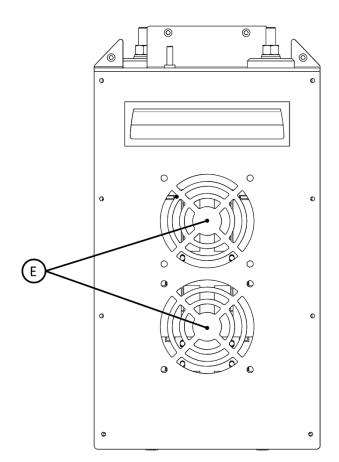


Figure 5 – HE 200 Ah module overview





#### Table 9 - Module connection overview

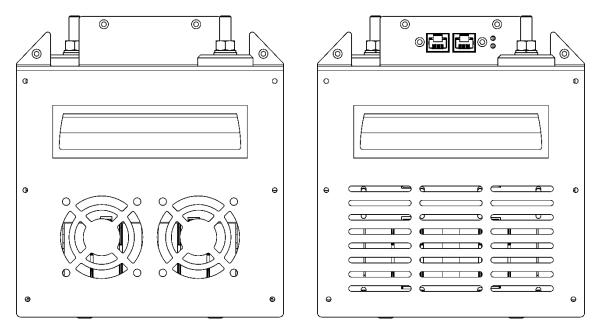
Part	Description
А	Positive power connection (including fuse). M8 bolt connection.
В	Equipotential bonding connection (only available on the (M12-HV) option).
С	CAN-Bus communication, either RJ45 or M12.
D	Negative power connection. M8 bolt connection.
E	Cooling fans (not for HE 300Ah)



### 6.1.1 Overview of all models

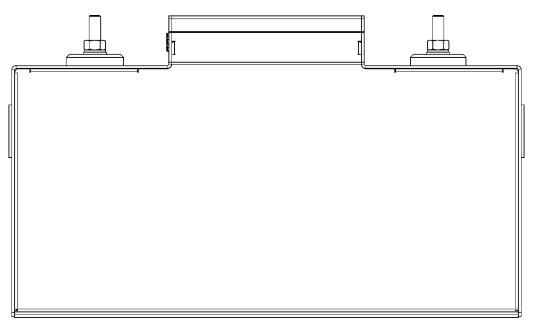
An overview of every battery model is shown below. For dimension check chapter 13.

# MGHE240100, MGHE241100, MGHE242100 (HE 100Ah)



Rear

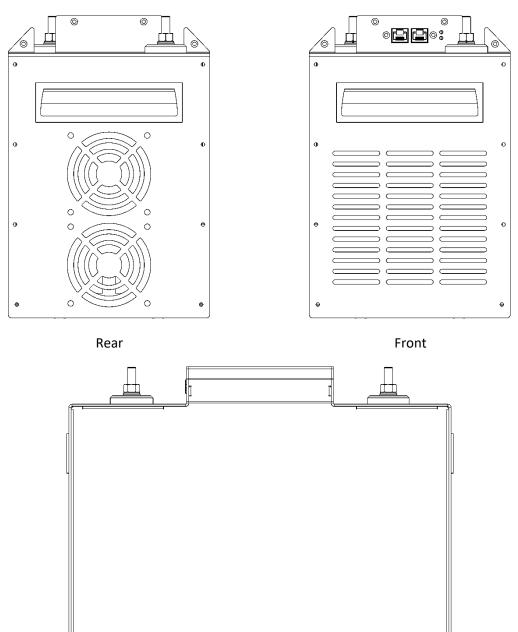
Front



Side



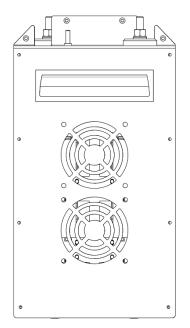
# MGHE240150, MGHE241150, MGHE242150 (HE 150Ah)

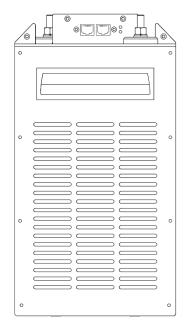


Side



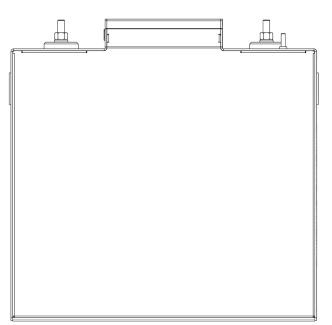
# MGHE240200, MGHE241200, MGHE242200 (HE 200Ah)



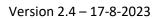


Rear

Front

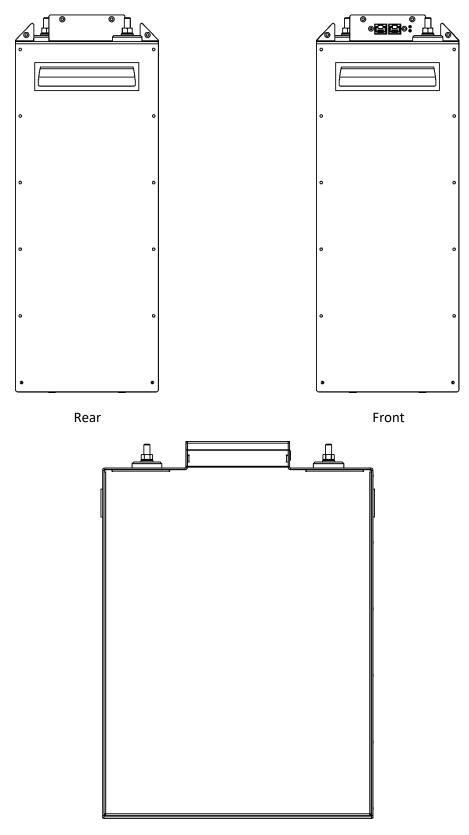


Side





# MGHE240300, MGHE241300, MGHE242300 (HE 300Ah)



Side



## 6.2 Connections details

Each battery module contains two CAN-Bus connectors to connect to the MG Master BMS and to the next battery, if any.

This CAN-Bus connection is used for several functions:

- Data communication between battery module(s) and master BMS;
- The battery module uses the V+ to enable the power of the internal BMS;

The HE Series have the option to have RJ45 or M12 CAN-Bus connectors.

### 6.2.1 RJ45 CAN-bus connector details

The standard connectors in the HE Series are the RJ45 CAN-Bus connectors.

### 6.2.1.1 Connector details

Typical cables that are used for the RJ45 CAN-Bus connections are standard CAT 5 Ethernet network patch cables.

Table 10 – RJ45 connector details

Pin	Description	Connector view
1		<b>RJ45 Pinout</b> 12345678
2		<b>RJ45 Pinout</b> 12345678 T-568B
3	GND	
4		
5		
6	V+	
7	CAN-H	
8	CAN-L	



### NOTICE:

Always use standard prefabricated Ethernet network patch cables (straight).



### 6.2.2 M12 CAN-bus connector details

The HE Series have the option to contain M12 CAN-Bus connectors.

### 6.2.2.1 Connector details

The connectors used for connecting the CAN-bus are all of the same type, namely a circular M12 connector with 5 positions and A-coded keying.

Table 11 - Circular M12 connector with 5 positions A-coded details

Pin	Description	Connector view
1	Shield	M12, 5-pin, A-coded
2	V+	
3	GND	
4	CAN-H	
5	CAN-L	
		Male Female

Cables to be used for the battery system are typically referred to as NMEA 2000 or DeviceNet compatible cables. The minimum requirements for cables are:

- Twisted pair connected to pins 4 and 5 for communication with a minimum wire cross sectional area of 0.2 mm<sup>2</sup> (24 AWG).
- Pair of conductors connected to pin 2 and 3 for power and HVIL with a minimum wire cross sectional area of 0.34 mm<sup>2</sup> (22 AWG).
- Cable with braided shielding connected to pin 1.



#### NOTICE:

Do not use sensor/actor cables. They often don't have any twisted pairs and are therefore not suitable for this application.



### 6.2.3 Power connections

The power connections on the battery module consists of two M8 bolt connections. One is the positive battery pole and one is the negative battery pole.

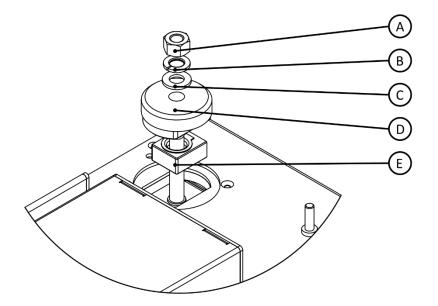


Figure 6 - Battery pole connection overview

Part	Description
А	Nut
В	Spring washer
С	Washer
D	Battery pole
E	Fuse (only positive battery pole)

### 6.2.3.1 Fuse

The positive battery pole contains a protection fuse. This fuse is a CF8 fuse. See chapter 8.6 for the replacement procedure.

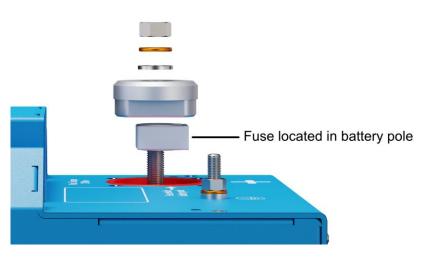


Figure 7 - Fuse location



Fuse types to use:

MG Fuse article number	Fuse current	Fuse manufacturer article number
MGFUSE1580150	150 A	Little fuse CF8 - 155.0892.6151
MGFUSE1580200	200 A	Little fuse CF8 - 155.0892.6201
MGFUSE1580225	225 A	Little fuse CF8 - 155.2892.6221
MGFUSE1580250	250 A	Little fuse CF8 - 155.0892.6251
MGFUSE1580300	300 A	Little fuse CF8 - 155.0892.6301
MG4000034	-	Non-fused battery pole
		(negative battery pole)

Default fuse types:

Battery type	Default fuse installed
MGHE240100, MGHE241100, MGHE242100 (HE 100Ah)	150 A
MGHE240150, MGHE241150, MGHE242150 (HE 150Ah)	200 A
MGHE240200, MGHE241200, MGHE242200 (HE 200Ah)	300 A
MGHE240300, MGHE241300, MGHE242300 (HE 300Ah)	300 A



### NOTICE:

A broken fuse is indicated by measuring no voltage on the battery terminals. Before measuring the nut must be tightened first.



### WARNING:

For systems with a voltage above 58 VDC, a non-fused battery pole is mandatory. See chapter 6.2.3.2 and 8.6.1 for more information.



### WARNING:

In some cases it is required to replace the fuse for a smaller one according to the cable size or can be fused elsewhere in the circuit.

# 6.2.3.2 Non-fused battery pole

Replacing the fuse by a non-fused battery pole is needed in case the battery module is used in series above 58 V. This non-fused battery pole is actually a complete battery pole that replaces the battery pole with fuse holder. See chapter 8.6 for the replacement procedure.





# 6.3 Status indication

Figure 8 shows the location of the status indication LEDs. They are located next to the CAN-bus connections.

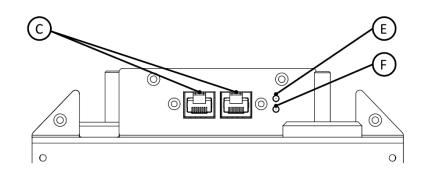


Figure 8 - Status LEDs overview

Part	Description
E	Green LED
F	Red LED

### 6.3.1 Indication

Table 12 shows the LED states and its meaning.

Table 12 - Status indication

Green LED	Red LED	Description
On	Off	Battery module is powered and internal BMS is operational.
On	On	Identification mode. The Red LED is turned on for a minute by the Diagnostic Tool to identify the battery.
Off	On	Battery module is in bootloader mode. Updating firmware is in progress.
Off	Off	Battery module is Off.



# 7 INTEGRATION REQUIREMENTS AND INSTRUCTIONS

This chapter describes the necessary requirements and instructions for integration of the battery module into the application.

# 7.1 Risk assessment

Performing a risk assessment for the integration of the battery system is mandatory. Depending on the application, specific rules might apply.

MG Energy Systems can supply the necessary basic documentation for risk assessment.



### NOTICE:

Before integration design check the applicable rules for the application where the battery system will be integrated in.

# 7.2 Location

The location of the battery system needs special attention, since some regulatory categorize Lithium-Ion battery systems as hazardous. Check for the local rules for the requirements of the battery system location in the used application.

General recommendations and requirements for the battery space with respect to the battery module are as following:

- Make sure the battery space is in accordance with the applicable rules.
- Ensure the battery space complies with the operating conditions of the batteries.
- Do not place the batteries next to a heat source.
- Take into account the placement requirements in chapter 7.3.

### 7.2.1 Environment

The battery modules has an IP rating of IP20 and must be placed in a space that is moisture and dust free, non-condensing and protected against fluid (water, oil etc.) ingress from top and bottom.



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### WARNING:

Moisture or water can damage the battery and its electronics. This might lead to dangerous situations.

### 7.2.2 Thermal management

The HE Series battery modules are air cooled. Therefore ambient temperature needs to be taken into account when selecting a space for the installation of the batteries.

- Make sure there is sufficient air flow in the battery space to dispose the heat rejected by the batteries and/or other equipment.
- The most optimized ambient temperature for the batteries is around 25 °C.





### NOTICE:

Take into account the heat rejection of other equipment in the same space of the batteries.



### NOTICE:

A significant decrease of cycle life will occur when the battery modules are used at high ambient temperatures.

If forced air ventilation is used for the battery room please make sure the environmental specifications are met. Temperature difference should in no way cause condensation on the battery module nor on other parts of the battery room.

### 7.2.2.1 Heat rejection

Table 13 shows the heat rejection versus charge and discharge rates for every HE battery model.

HE battery model	HE 100 Ah	
Nominal internal resistance	16 mOhm	
Cooling system	Active air cooling with fans	
Heat rejection	0.5 C = 40 W	
	1 C = 160 W	

Table 13 – Heat rejection versus charge/discharge rate.

HE battery model	HE 150 Ah
Nominal internal resistance	12 mOhm
Cooling system	Active air cooling with fans
Heat rejection	0.5 C = 68 W
	1 C = 270 W

HE battery model	HE 200 Ah
Nominal internal resistance	8 mOhm
Cooling system	Active air cooling with fans
Heat rejection	0.5 C = 80 W
	1 C = 320 W

HE battery model	HE 300 Ah
Nominal internal resistance	6 mOhm
Cooling system	Passive air cooling (convection)
Heat rejection	0.5 C = 135 W
	1 C = 540 W



### 7.2.2.2 Air cooling

Each HE battery excluding the HE 300Ah is equipped with fans for active cooling. Figure 9 shows the air flow direction through the battery module.

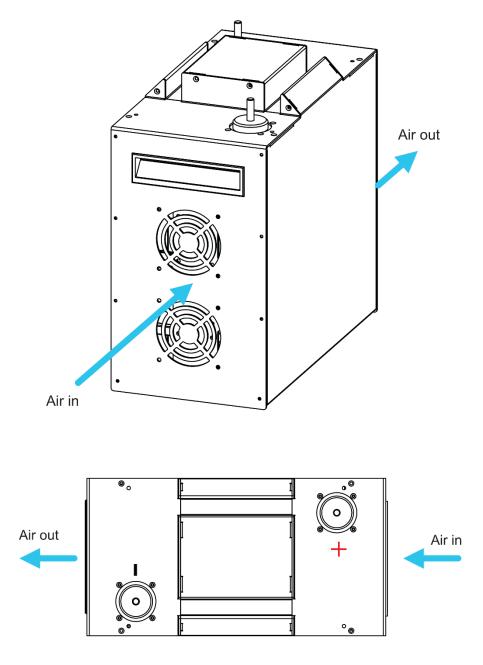


Figure 9 - Air flow through module

The fans will turn on/off at certain battery temperatures. The exact boundary limits when the fans will turn on and off can be found in chapter 11.

Fan specifications per battery module:

Battery model	Flow rate	Noise
HE 100Ah	82,2 m³/h	39 dBA
HE 200Ah and HE 150Ah	94,8 m³/h	39 dBA



# 7.3 Placement

This chapter will explain the design requirements for placement of the battery modules.

### 7.3.1 Placement in battery box

It is mandatory to place the battery modules in a steel box or sealed compartment with fire retardant properties. This will protect the battery modules from external environmental abuse such as water or moisture ingress and fire. It also protect the environment from a potential battery fire.

Requirements to the battery box:

- Preferred isolated for 60 minutes fire retardant (A60).
- Fluid and gas tight.
- Gas exhaust connection to outside (safe area).
- Manual or automatic flooding option of this battery box.
- Temperature sensor.
- Smoke sensor.
- No electrical switching equipment or junction boxes inside.
- Place the battery modules 10 mm from the bottom.
- Accessibility for commissioning and service of battery modules must be maintained.



### NOTICE:

Respect the thermal management notes of the battery module in chapter 7.2.2 when used in sealed spaces or compartments.



#### NOTICE:

Always install the ingress cover protection on top of each battery module (article number: MG4000267).



### NOTICE:

Also find the guidelines for placement of batteries in a battery box on the <u>MG</u> <u>Download Center</u>



### 7.3.2 Positioning the battery

The battery module may be placed upwards and on its side. Figure 10 and Figure 11 shows the possible positions that are allowed.

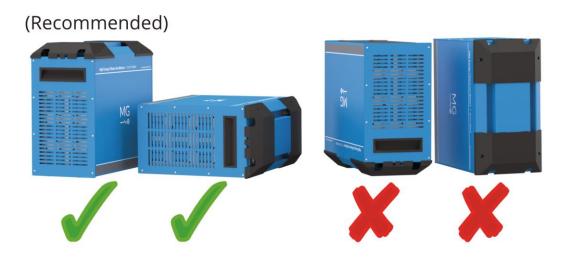


Figure 10 - Mounting positions of the HE 100, HE 150 and HE200 models

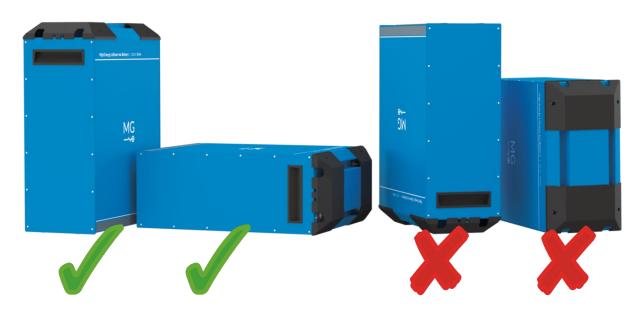


Figure 11 - Mounting positions of the HE300 model



### 7.3.3 Positioning considering air flow

The airflow of the battery modules must be considered when positioning the battery modules certain positions. The airflow of one battery may not be used as input flow for the next battery. This will cause temperature differences and thus imbalance in the modules. Figure 12 show examples of correct and wrong installs.

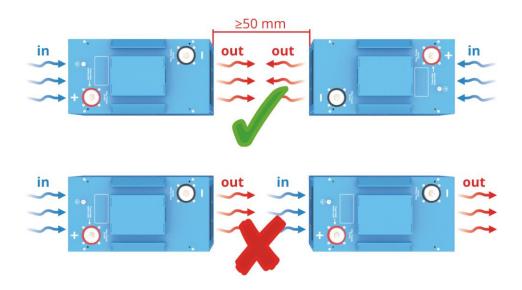


Figure 12 - Module positioning considering air flow

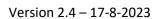
### 7.3.4 Mounting considerations

Mounting of the battery modules can be either done by straps or brackets.



#### NOTICE:

Mounting brackets or straps are not within the scope of delivery.





### 7.3.5 Battery module spacing requirements

Figure 13 shows the minimum spacing of the battery modules. It is mandatory to maintain a clearance of 10 mm from all sides of the battery module. There is a keep out clearance of 50 mm at the front and back of the modules with fans installed. This will give the air cooling sufficient flow to cool the battery module.

#### 7.3.5.1 Spacing requirements HE 100-150-200 models



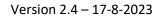
Figure 13 - Battery spacing requirements applicable to HE 100-150-200 models



# 7.3.5.2 Spacing requirements HE300 model



Figure 14 - Battery spacing requirements applicable to HE300 model





# 7.4 Electrical

This chapter describes the installation and connections of the electrical wiring.

### 7.4.1 Power cables

Cable lengths need to be taken into account when designing a battery system. Batteries can be placed in parallel, for example in 24 VDC systems, or in series up to 144 VDC.

### NOTICE:

- Use the correct cable type for the applicable system voltage.
- Use the correct fuses for the applicable cable cross-section and voltage.
- We recommend to size the cables to limit voltage drop to 1% or less.



#### NOTICE:

Cable lug and battery must be cleaned before connection to ensure a low resistance connections. Check these power connections for excessive temperatures during a load test.

# 7.4.2 Parallel configuration

The battery module can set in parallel to create a larger system capacity. The MG Master BMS can handle up to 96 HE battery modules. Meaning that a 24 VDC system can have 96 HE battery modules in parallel. For a 48 VDC system is would be 48 HE battery modules.



### CAUTION:

Make sure the voltage of each battery module is equal when connecting them in parallel. Excessive high uncontrolled currents can flow between battery modules when the voltage is not equal. This can damage the batteries and might lead to other damage or injury.



### NOTICE:

The power cables of each battery module need to have matching lengths as good as possible when connecting battery modules in parallel.

Battery modules can be connected separately in parallel to a Master LV. It has four power connection positions where four batteries could be connected. Refer to the Master LV manual for more information.

Figure 15 shows the most basic parallel connection that is possible. The power connection of each battery is directly connected to a Master LV.



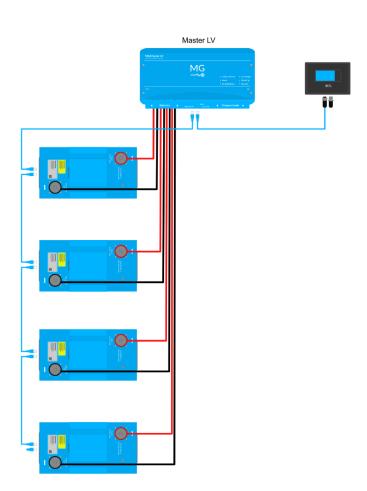


Figure 15 - Four battery module connected in parallel on a single Master LV. Cables must have matching lengths.

There are multiple options when connecting more than four batteries in parallel.

- 1. Paralleling at the battery modules.
- 2. Paralleling using the Distributor LV.
- 3. Paralleling using a custom bus bar connection system.



# 7.4.2.1 Paralleling at the battery modules

Paralleling at the battery modules makes it possible to connect more than four battery modules to a Master LV or other DC distribution. Important is that the cable lengths of the battery modules must be as equal as possible to prevent too much differences during charging and discharging.

Figure 16 shows the connection of two paralleled groups of two battery modules. The two batteries in a group are connected crosswise. This is done to make sure the two batteries have the same total length of power cables and thus the same cable resistance.

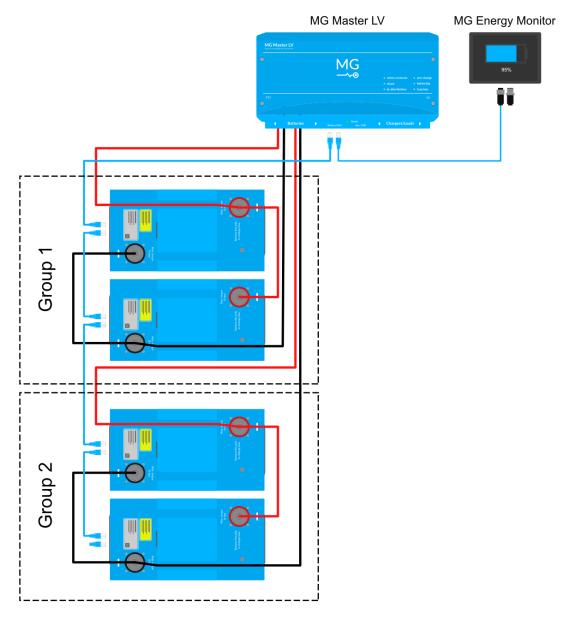


Figure 16 - Example of battery modules paralleled in groups



#### NOTICE:

- Do not create groups larger than five batteries;
- Only use this method in 24 V or 48 V systems;



Figure 17 shows the same paralleling method, but used for a 48 V system where battery modules are connected in series.

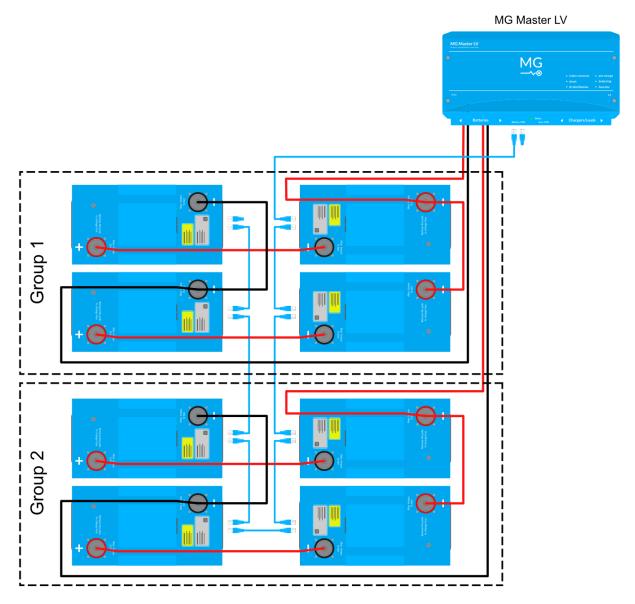


Figure 17 - Example of 48 V system with paralleled groups



# 7.4.3 Paralleling using the Distributor LV

Another option to parallel battery modules is to use the MG Distributor LV (MGLVDIST01001). Basically this DC distribution box has a positive and negative bus bar with the possibility to place fuses. Refer to the manual of the MG Distributor LV for more details.

Figure 18 shows an example of paralleling battery modules using the MG Distributor LV's.

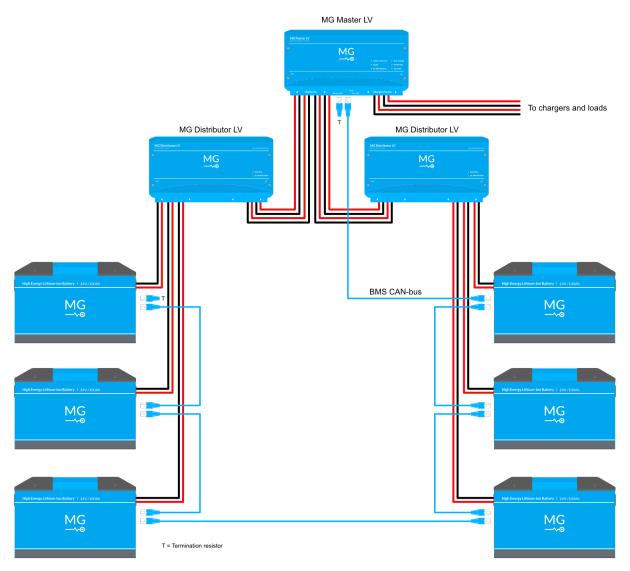


Figure 18 - Example of parallel connection with MG Distributor LV's

### 7.4.4 Paralleling using a custom bus bar connection system

Designing a custom DC-busbar system is beyond the scope of this manual.



### 7.4.5 Series configuration

The battery modules can be connected in series up to 144 VDC which requires the use of the MG Master HV.

Table 14 shows the maximum number of battery modules in series per battery type.

 Table 14 - Maximum number of modules in series per battery type.

Article number	Voltage range	Maximum number of modules in series
MGHE240100, MGHE241100		
MGHE240150, MGHE241150	24 VDC up to	4
MGHE240200, MGHE241200	96 VDC	4
MGHE240300, MGHE241300		
MGHE242100, MGHE242150, MGHE242200,	24 VDC up to	C
MGHE242300	144 VDC	6



#### WARNING:

The fuse in each battery pole must be replaced by a non-fused battery pole when connecting more than 2 batteries in series. See chapter 6.2.3.1 for details and article number.

#### WARNING:

- Make sure high voltage battery systems are not accessible by nonauthorized people or personnel.
- Mark the space of the high voltage battery installation with warning signs of ELECTRICAL SHOCK and the applicable signs according to the local rules and regulation.



#### NOTICE:

Some regulations require a manual battery or safety disconnect.

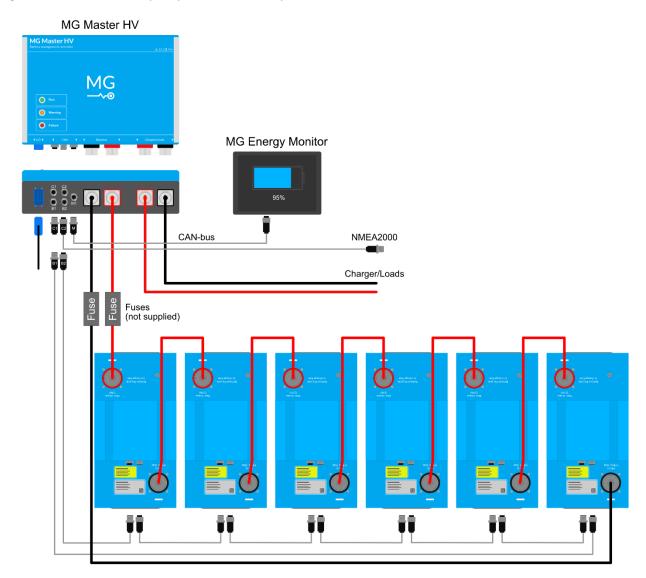


Figure 19 shows an example system of 6 battery modules in series connected to a MG Master HV.

Figure 19 – Series configuration example



#### WARNING:

In systems with voltages > 58 V an insulation monitor is required.



#### NOTICE:

- Use the correct cable type for the applicable system voltage.
- Use the correct fuses for the applicable cable cross-section and voltage.



# 7.4.6 Charger

Any charger with constant voltage (CV) constant current (CC) charging can be connected to the MG battery system. The most important is that the charger can be stopped by the MG Master BMS when the batteries are fully charged. Therefore the charger needs to have the ability to stop and start it remotely with a contact. There are also a number of chargers available that are digitally controlled by the MG Master BMS. Refer to the MG Master LV or MG Master HV manual for more details.

# 7.4.6.1 Charger settings

Chargers that are controlled with on/off need to use the following voltage settings.

Absorption voltage	29,1 VDC
Float voltage	28,0 VDC

This is the voltage setting for one battery. Multiply this by the number of batteries in series for system voltages > 24 VDC.



# 8 INSTALLATION

Read the installation instructions in this chapter before commencing installation activities.

Additional information for installation:

- Installation video: <u>HE 100-150-200</u> and <u>HE300</u>
- Quick installation guide: <u>HE 100-150-200</u> and <u>HE300</u>
- Technical drawings
- Application Notes

#### WARNING:

Before continuing make sure the following instructions are met:

- Ensure that the connection cables are provided with fuses and circuit breakers.
- Never replace a protective device by a component of a different type. Refer to the ordering information sections of this manual or contact manufacturer for a correct replacement.



- Before switching the device on, check whether the available DC bus voltage range conforms to the configuration of the product as described in the manual.
- Ensure that the equipment is used under the correct operating conditions. Never operate it in a wet or dusty environment.
- Ensure that there is always sufficient free space around the product.
- Install the product in an environment that can sustain some heat. Ensure therefore that there are no chemicals, plastic parts, curtains or other textiles, etc. in the immediate vicinity of the equipment.

### ELECTRICAL HAZARD:



- Wear applicable personal protective equipment when working on a battery system.
- Use insulated tools when working on a battery system.
- Make sure the locale health and safety regulations for working on battery systems are followed.

# 8.1 Tooling

The required tools during installation are the following:

- Phillips screwdriver PH1 (insulated);
- Torque wrench M5 (8 mm) + M8 (13 mm) (insulated);



# 8.2 Installation procedures

Below the basic installation procedures at battery module level.

- 1. Mount the battery module: mounting procedure;
- 2. Equipotential bonding of the battery modules: equipotential bonding procedure;
- 3. Connect the battery module electrically: electrical connection procedure;
- 4. Installing the top ingress protection cover;
- 5. Replacing the internal fuse: Fuse replacing procedure;



#### NOTICE:

During installation a check form needs to be used to log the installation procedure. This log will be checked during commissioning.

# 8.3 Mounting procedure

The battery module has no specific mounting points. Instead it can be mounted with brackets or straps as stated in chapter 7.3.4.

### 8.4 Electrical connection procedure

The battery module can be used in combination with other battery modules of the same type and always in combination with a MG Master BMS.

Before any electrical connection can be performed, the top covers from the battery module must be removed.





#### **ELECTRICAL HAZARD:**

The battery modules can be placed in series up to 144 VDC. Make sure to wear proper insulation gloves and safety goggles.



### ELECTRICAL HAZARD:

Before connecting the DC cables, make sure the other ends are protected or connected.



# 8.4.1 Equipotential bonding connection procedure

The equipotential bonding connection is located on top of the battery module next to the positive power connection as shown in chapter 6.1. Equipotential bonding connection scheme and the required wire cross-section depend on local standards and regulation. The typical used wire cross-section is 6 mm<sup>2</sup>.

When the system voltage is > 58 Vdc then connect a 6  $\text{mm}^2$  wire from the equipotential bonding point of each battery module in the system to a Protective Earth (PE). Tighten it with 4Nm.

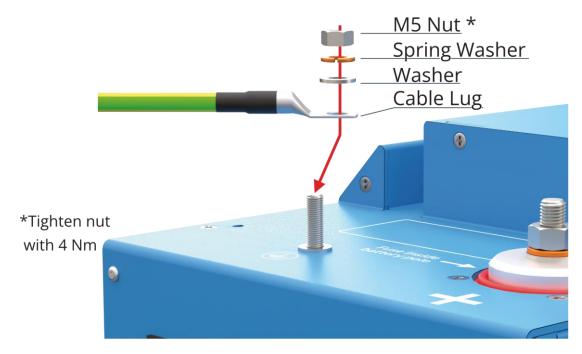


Figure 20 - Connection example of Equipotential bonding

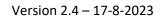


#### **ELECTRICAL HAZARD:**

Make sure the equipotential bonding cable is routed with free clearance of the battery pole.



Figure 21 - Wrong routing of equipotential bonding wire





#### 8.4.2 Positive and negative power connection procedure

Before connecting any power cable make sure the routing of the power cables is made properly. Figure 22 shows a wrong connection of the power cable which will interfere with the CAN-Bus connectors and protection cover. Figure 23 shows a good connection of the power cable. Refer to chapter 7.4 for details about the power connections.



Figure 22 - Wrong connection of power cable

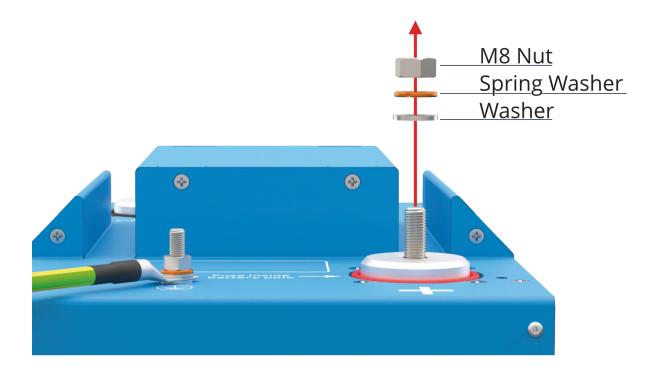


Figure 23 - Good connection of power cable



Below the procedure for connecting the power cables to the battery.

1. Remove the nut, spring washer and washer from the positive battery pole.

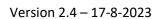




#### NOTICE:

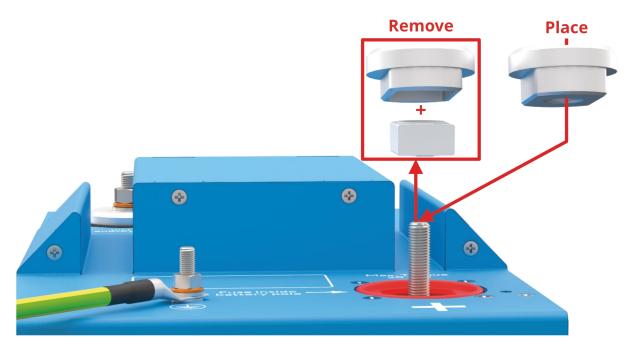
When removing the nut and washers from the battery pole, it will become loose. This is normal. When the cable is connected and the nut and washers are back in place it will be tightened again.

2. Clean the battery pole and the cable lug's contact surfaces for a low resistance connection.

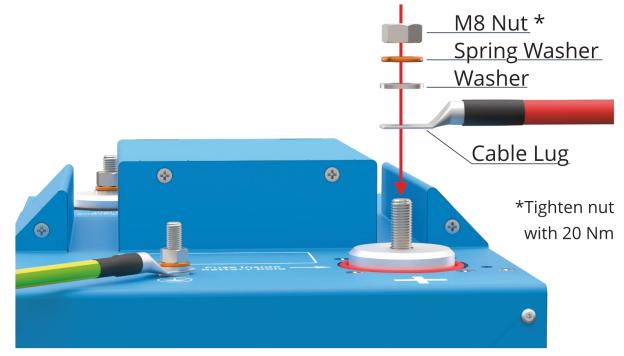




 Depending on the system voltage or specific system design the battery fuse must be removed. In case of system voltage > 58 Vdc: replace battery pole + fuse with non-fused battery pole.

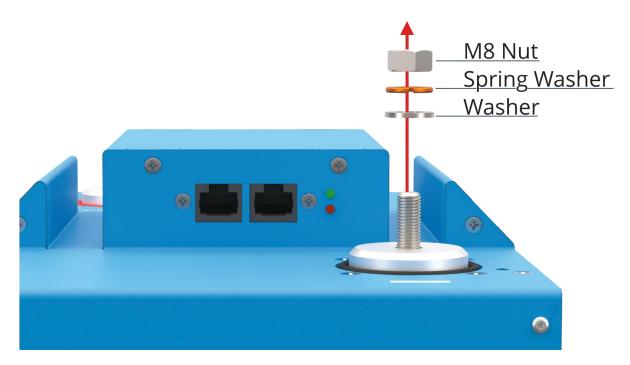


4. Connect the positive power cable with M8 cable lug to the M8 bolt as shown and place back the washer, spring washer and nut. Tighten the nut with a torque of 20 Nm.

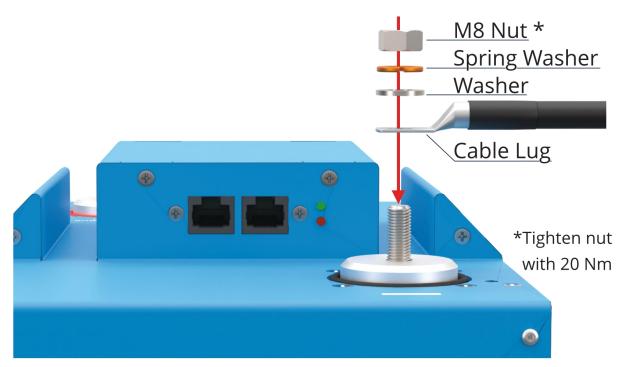


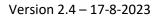


5. Remove the nut, spring washer and washer from the negative battery pole.



- 6. Clean the battery pole and the cable lug's contact surfaces for a low resistance connection.
- 7. Connect the negative power cable with M8 cable lug to the M8 bolt as shown and place back the washer, spring washer and nut. Tighten the nut with a torque of 20 Nm.







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WARNING: Make sure the cable lug is directly mounted to the battery pole without any washers or nuts in between.



# WARNING:

Stacking of multiple cable lugs is possible however we strongly advise against it. Connection resistance increases which, in time, might lead to excessive heat generation.



# ELECTRICAL HAZARD:

Make sure power cables are routed properly to avoid sharp edges and other possible causes of a short-circuit. It is recommended to protect the cables with a conduit system.



### 8.4.3 CAN-bus connection procedure

The battery modules communicated with a CAN-bus system to the MG Master BMS. This connection can either be with RJ45 or M12 connectors depending on the battery type. The same topology is used for both connector types. However, the MG Master LV and MG Master HV can have different connection configurations. For more information about the CAN-bus communication connection possibilities, refer to the MG Master LV, MG Master HV manual.

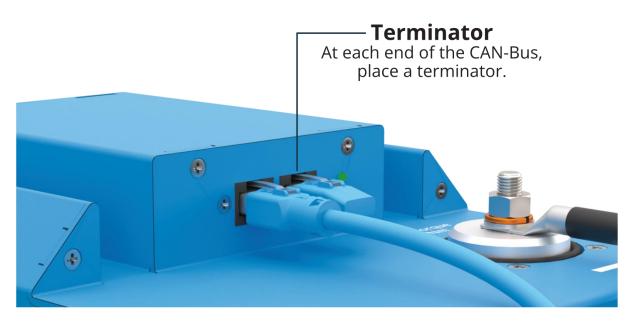


Figure 24 - RJ45 battery connection

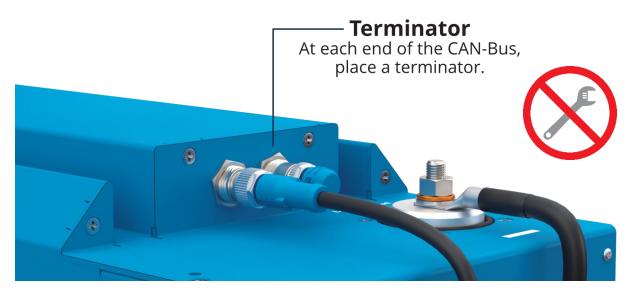
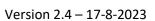


Figure 25 - M12 battery connection



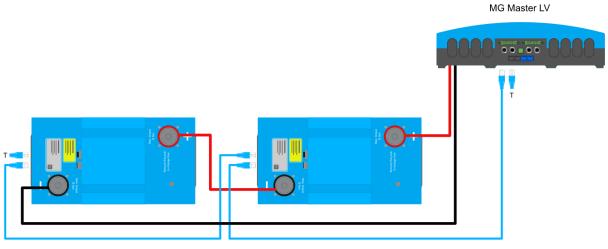


### 8.4.3.1 Basic connection

The most basic connection is as following:

- 1. Start with a CAN-bus cable at the MG Master BMS, the Battery CAN-Bus, and go to the first battery.
- 2. Connect from the first to the second battery. Repeat this until the last battery module.
- 3. Place a termination resistor at the end and begin of the CAN-bus network.

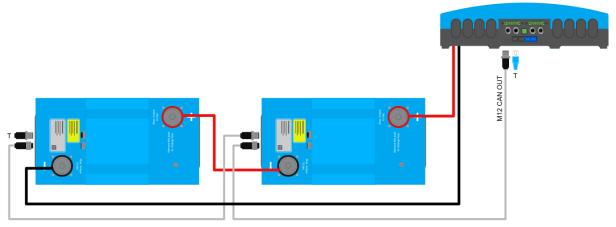
RJ45 connection:



T = Termination resistor

M12 connection:

MG Master LV

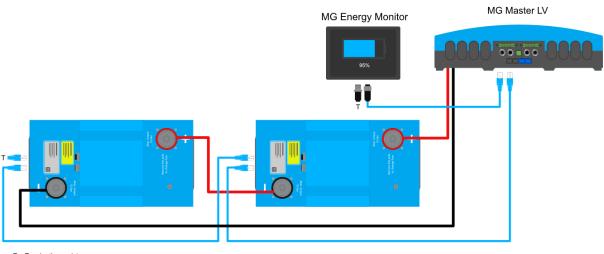


T = Termination resistor



# 8.4.3.2 Example including MG Energy Monitor

In this example an MG Energy Monitor is connected to the battery system using M12 to RJ45 converter cables.



T = Termination resistor



### WARNING:

Use the termination resistors delivered with the MG Master BMS. 3<sup>rd</sup> party termination resistors could damage the devices, because pinning could be different.



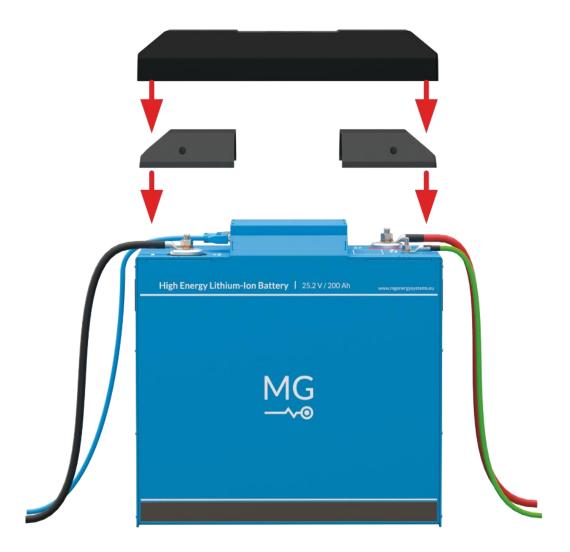
# 8.5 Installing the top ingress protection cover

The top ingress protection cover is used to protect the battery module against the ingress of liquids from the top. This chapter describes the installation of the cover.



Figure 26 - Top ingress protection cover for HE series

The two black covers needs to be mounted before the top ingress protection cover can be mounted.





#### 8.5.1 Placing the cover

The cover can be placed over the modules even when the cables are connected. The flexibility of the cover makes it to fit to almost every existing installation. In some cases the cover must be cut to make it fit. See chapter 8.5.3 for details on cutting the cover.

1. Place the ingress protection cover at three corners first as shown in Figure 27.



Figure 27 - First place three corners

2. Press the last corner in place until it snaps.



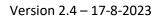
Figure 28 - Press the last corner





Figure 29 shows an example of a cover installed on a battery module.

Figure 29 - Example of cover in installation





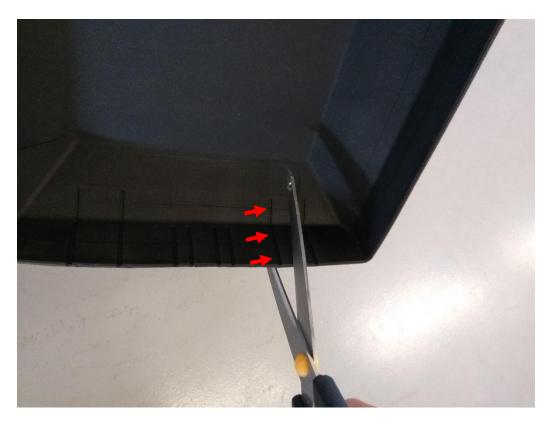
### 8.5.2 Removing the cover

- 1. Pull **one** corner away from the battery
- 2. Lift the cover to release it.



# 8.5.3 Cutting the cover

If cutting is required use the cut lines at the inside of the cover as guide.



**Do not** remove the flap because it prevents water drips of entering the battery module or cable.



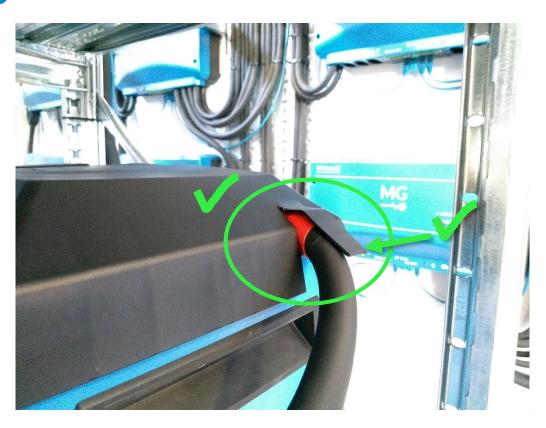


Figure 30 - Example to cutting out cable release.



# 8.6 Fuse replacing procedure

Replacement of the fuse requires the battery system to shut down. The fuse can be replaced with a new fuse or with a non-fused battery pole.

# WARNING:

- When replacing the fuse with a non-fused battery pole, the fuse for the string of batteries needs to be installed separately in the system.
- Do not use the battery unfused.

# 8.6.1 Non-fused battery pole

The non-fused battery pole is actually a regular negative battery pole. Figure 31 shows the difference between the two.

Non-fused Battery pole

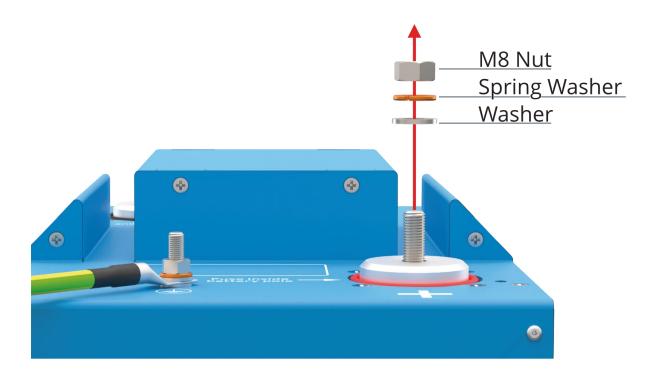




Figure 31 - Overview of negative and positive battery pole.

### 8.6.2 Replacement instructions

1. Remove the nut, spring washer and washer from the positive battery pole.

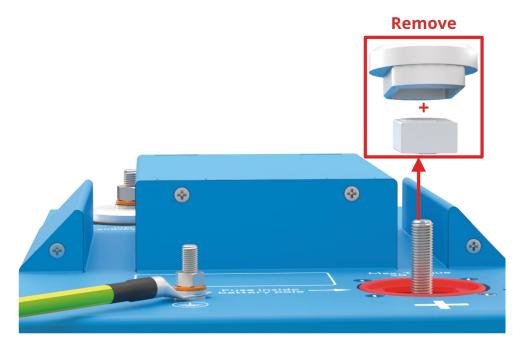




# NOTICE:

When removing the nut and washers from the battery pole, it will become loose. This is normal. When the cable is connected and the nut and washers are back in place it will be tightened again.

2. Remove positive battery pole and fuse.



- 3. Now the fuse can be checked and replaced with a new one or it can be replaced with a nonfused battery pole. If the fuse is replaced with a non-fused battery pole then clean the battery pole with a fine sanding block (scotch-brite). Recommended is to add an electrical joint compound for better conduction.
- 4. Before connecting the power cable, the voltage of the battery module needs to be measured to check if it is the same as the parallel connected batteries. If not then charge/discharge the batteries separately to the same level.
- 5. Connect the power cables with the instructions of chapter 8.4.2.



# 9 COMMISSIONING

Table 15 shows a list of points that need to be checked after installation.

Table 15 - Commissioning steps procedure

Description
Is a risk assessment performed?
Are the location and placement requirements in chapter 7.2 and 7.3 met?
Are the batteries installed in a location where there is no possibility fluids can enter
the battery module from the top or bottom? For example installation under the
 seams of hatches.
Are the battery modules clean from any dust, metal pieces and loose wires?
Are the equipotential bonding cables connected, if applicable?
Are the battery fuses replaced in case of system voltage of > 58 Vdc?
Are all battery pole power connection tightened with 20 Nm?
Are all CAN-Bus cables connected?
Are CAN-bus termination resistors installed in the correct way?
Is there any equipment connected directly to the batteries? This is not allowed.
Is top ingress protection cover installed?
Perform a charge/discharge test run and measure the temperature of the battery
terminals during the test.
Is there excessive heat generation in the system or system components?
Make pictures of the installation.
Send the pictures and this form together with the system commissioning form to
<pre>support@mgenergysystem.eu with the subject: <project name=""> - Commissioning.</project></pre>



### NOTICE:

For the system commissioning procedure, refer to the manual of the MG Master LV or MG Master HV. If no commissioning procedure is available in the manual, contact MG Energy Systems.

# **10 SERVICE**

# 10.1 Maintenance

For maintenance it will be sufficient to inspect the following points once a year:

- Check the electrical connections on torque.
- Check if all communication connections are mated.
- Check for traces of water, oil, moisture, any other fluids or dust.
- Check for signs of corrosion.
- Clean the device.
- Check status with the <u>MG Diagnostic Tool</u>, <u>MG Connect App</u> or <u>MG Energy Portal</u>.



### ELECTRICAL HAZARD:

Do not poor or spray water directly onto the device. When cleaning the device be aware that the connected battery string is a permanent energy source. Even when the device is turned off, the battery power connections might carry dangerous voltage levels.

# 10.1.1 Cleaning

Cleaning of the device is best done using a dry or slightly damp cloth. Limit the use of cleaning agents. If a cleaning agent is to be used, use an electrically non-conductive cleaning agent is advised.

It is important to keep the battery spaces clean and tidy in order to minimise the need for cleaning. Prevent the use of moisture, vaporizing agents, oil, grease, etc. in the vicinity of the device.

# 10.2 End-of-life

The battery module is considered end-of-life if the SOH is decreased to 70 %. After this period it is strongly advised to replace the battery module to ensure safety.

# 10.3 Disposal

Batteries marked with the recycling symbol must be processed locally via a recognized recycling agency. By agreement, they may be returned to the manufacturer. Batteries must not be mixed with domestic or industrial waste. Before disposal it is recommended to discharge the battery module to 0 VDC.



# **11 BOUNDARY LIMITS**

The boundary limits that are used by the master for the battery modules are listed in this chapter. A level will be triggered when a boundary condition is true for a defined period of time.

Battery thresholds are compatible with the following master BMS firmware versions or higher:

- Master HV 1.13 or higher
- Master LV 1.23 or higher

# 11.1 HE 25.2 V / 100-150-200 Ah Battery Module

Boundary limits are defined to keep the battery within manufacturer's specifications.

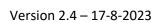
The tables with the boundary limits consist of:

- Name, description of the situation;
- Action, action on respond of the boundary, set/clear or failsafe;
- Boundary condition, contains a value that is needed for an action in combination with the time;
- Time that the boundary condition has to be present before it will be triggered. Times
  indicated with "+" start counting if the previous boundary condition above is set.

# 11.1.1 Cell voltage

 Table 16 Cell voltage boundary limits slave BMS

		Boundar		
Name	Level	Economic	Performance	Time
Almost charged	Set	>= 3950 mV	>= 4100 mV	10 sec.
	Clear	< 3900 mV	< 4050 mV	10 sec.
Charged	Set	>= 4000 mV	>= 4150 mV	+10 sec.
	Clear	< 3950 mV	< 4100 mV	10 sec.
Over voltage warning	Set	>= 4100 mV	>= 4175 mV	+20 sec.
	Clear	< 4000 mV	< 4150 mV	20 sec.
Over voltage critical	Failsafe	>= 4200 mV	>= 4200 mV	+5 sec.
Almost discharged	Set	<= 3	325 mV	10 sec.
	Clear	> 33	375 mV	10 sec.
Discharged	Set	<= 3	000 mV	+10 sec.
	Clear	> 33	325 mV	10 sec.
Under voltage warning	Set	<= 2750 mV		+20 sec.
	Clear	> 30	)00 mV	20 sec.
Under voltage critical	Failsafe	<= 2600 mV		+5 sec.





### **11.1.2** Cell temperature charging

Table 17 Cell temperature charging boundary limits slave BMS

		Bounda		
Name	Level	Economic	Performance	Time
Over temperature alert	Set	>= 43 °C	>= 48 °C	5 sec.
	Clear	< 42 °C	< 47 °C	5 sec.
Over temperature	Set	>= 45 °C	>= 50 °C	+20 sec.
	Clear	< 43 °C	< 48 °C	20 sec.
Over temperature critical	Failsafe	>= 50 °C	>= 55 °C	+60 sec.
		charg	charge current	
		> 5% battery capacity		
		•		
Under temperature alert	Set	<:	= 1 °C	5 sec.
	Clear	>	• 2 °C	5 sec.
Under temperature	Set	<= 0 °C		+20 sec.
	Clear	>	- 1 °C	20 sec.
Under temperature critical	Failsafe	<= -5 °C and charge current		+60 sec.
		> 5% bat	> 5% battery capacity	

#### 11.1.3 Cell temperature discharging

Table 18 Cell temperature discharging boundary limits slave BMS

		Boundary condition		
Name	Level	Economic	Performance	Time
Over temperature alert	Set	>=	53 °C	5 sec.
	Clear	<	52 °C	5 sec.
Over temperature	Set	>=	55 °C	+20 sec.
	Clear	<	53 °C	20 sec.
Over temperature critical	Failsafe	>= 60 °C		+60 sec.
Under temperature alert	Set	<= -19 °C		5 sec.
	Clear	> -18 °C		5 sec.
Under temperature	Set	<= -20 °C		+20 sec.
	Clear	> -19 °C		20 sec.
Under temperature critical	Failsafe	<= -25 °C and discharge current		+60 sec.
		> 10% bat	tery capacity	

#### 11.1.4 Power terminal temperature

Table 19 Power terminal temperature boundary limits slave BMS

		Boundar		
Name	Level	Economic Performance		Time
Over temperature alert	Set	>= 60 °C		5 sec.
	Clear	< 59 °C		5 sec.
Over temperature	Set	>= 70 °C		+20 sec.
	Clear	< 60 °C		20 sec.
Over temperature critical	Failsafe	>= 80 °C		+60 sec.



#### 11.1.5 Current

Table 20 Current boundary limits slave BMS

		Bounda		
Name	Level	Economic	Performance	Time
Charging over current warning	Set	> 0.6C	> 1C	10 sec.
	Clear	<= 0.6C	<= 1C	10 sec.
Discharging over current warning	Set	> 1.0C	> 1.5C	10 sec.
	Clear	<= 1.0C	<= 1.5C	10 sec.

#### 11.1.6 Balancing

 Table 21 Balancing boundary limits slave BMS

		Boundary condition		
Name	Level	Economic Performance		Time
Offset cell voltage		> 5 mV		5 min.
Balancing cell voltage		>= 3805 mV		5 min.
Battery pack current		current within ±5% battery		5 min.
		capacity		

#### **11.1.7** Deviation voltages and temperatures

Table 22 Deviation voltage and temperature boundary limits slave BMS

		Boundary co	Boundary condition		
Name	Level	Economic	Performance	Time	
Deviation cell voltage	Set	<ul> <li>Difference highest ar</li> </ul>	nd lowest cell	4-6 min.	
		voltage >= 300 mV;			
		Iowest cell voltage >	= 3325;		
		■ current within ±5% b	attery capacity		
	Clear	<ul> <li>Difference highest ar</li> </ul>	nd lowest cell	4-6 min.	
		voltage < 240 mV;	voltage < 240 mV;		
		Iowest cell voltage >			
		■ current within ±5% b	attery capacity		
Deviation cell temperature	Set	Difference highest	and lowest cell	4-6 min.	
		temperature	>= 15 °C		
	Clear	Difference highest	and lowest cell	4-6 min.	
		temperature	e < 12 °C		



# 11.2 HE 25.2 V / 300 Ah Battery Module

Boundary limits are defined to keep the battery within manufacturer's specifications.

The tables with the boundary limits consist of:

- Name, description of the situation;
- Action, action on respond of the boundary, set/clear or failsafe;
- Boundary condition, contains a value that is needed for an action in combination with the time;
- Time that the boundary condition has to be present before it will be triggered. Times
  indicated with "+" start counting if the previous boundary condition above is set.

#### 11.2.1 Cell voltage

 Table 23 Cell voltage boundary limits slave BMS

		Boundary condition		
Name	Level	Economic	Performance	Time
Almost charged	Set	>= 3950 mV	>= 4100 mV	10 sec.
	Clear	< 3900 mV	< 4050 mV	10 sec.
Charged	Set	>= 4000 mV	>= 4150 mV	+10 sec.
	Clear	< 3950 mV	< 4100 mV	10 sec.
Over voltage warning	Set	>= 4100 mV	>= 4175 mV	+20 sec.
	Clear	< 4000 mV	< 4150 mV	20 sec.
Over voltage critical	Failsafe	>= 4200 mV	>= 4200 mV	+5 sec.
Almost discharged	Set	<= 3	325 mV	10 sec.
	Clear	> 33	375 mV	10 sec.
Discharged	Set	<= 3	000 mV	+10 sec.
	Clear	> 33	325 mV	10 sec.
Under voltage warning	Set	<= 2750 mV		+20 sec.
	Clear	> 30	)00 mV	20 sec.
Under voltage critical	Failsafe	<= 2	<= 2600 mV	



# 11.2.2 Cell temperature charging

Table 24 Cell temperature charging boundary limits slave BMS

		Bounda		
Name	Level	Economic	Performance	Time
Over temperature alert	Set	>= 38 °C	>= 43 °C	5 sec.
	Clear	< 37 °C	< 42 °C	5 sec.
Over temperature	Set	>= 40 °C	>= 45 °C	+20 sec.
	Clear	< 38 °C	< 43 °C	20 sec.
Over temperature critical	Failsafe	>= 50 °C	>= 55 °C	+60 sec.
		charg	charge current	
		> 5% battery capacity		
Under temperature alert	Set	<:	= 1 °C	5 sec.
	Clear	>	• 2 °C	5 sec.
Under temperature	Set	<= 0 °C		+20 sec.
	Clear	> 1 °C		20 sec.
Under temperature critical	Failsafe	<= -5 °C and charge current		+60 sec.
		> 5% bat	tery capacity	

#### 11.2.3 Cell temperature discharging

Table 25 Cell temperature discharging boundary limits slave BMS

		Boundary condition		
Name	Level	Economic	Performance	Time
Over temperature alert	Set	>= 48 °C		5 sec.
	Clear	< 47 °C		5 sec.
Over temperature	Set	>= 50 °C		+20 sec.
	Clear	< 48 °C		20 sec.
Over temperature critical	Failsafe	>= 60 °C		+60 sec.
Under temperature alert	Set	<= -19 °C		5 sec.
	Clear	> -18 °C		5 sec.
Under temperature	Set	<= -20 °C		+20 sec.
	Clear	> -	-19 °C	20 sec.
Under temperature critical	Failsafe	<= -25 °C and discharge current		+60 sec.
		> 10% bat	tery capacity	

#### 11.2.4 Power terminal temperature

Table 26 Power terminal temperature boundary limits slave BMS

		Boundary condition		
Name	Level	Economic	Performance	Time
Over temperature alert	Set	>= 60 °C		5 sec.
	Clear	< 59 °C		5 sec.
Over temperature	Set	>= 70 °C		+20 sec.
	Clear	< 60 °C		20 sec.
Over temperature critical	Failsafe	>= 80 °C		+60 sec.



#### 11.2.5 Current

Table 27 Current boundary limits slave BMS

		Bounda		
Name	Level	Economic	Performance	Time
Charging over current warning	Set	> 0.7C		10 sec.
	Clear	<= 0.7C		10 sec.
Charging over current critical	Failsafe	> 1.8C (HE 300Ah = 1.2C)		+20 sec.
Discharging over current warning	Set	> 1.0C		10 sec.
	Clear	<=	: 1.0C	10 sec.

#### 11.2.6 Balancing

 Table 28 Balancing boundary limits slave BMS

		Boundary condition		
Name	Level	Economic	Performance	Time
Offset cell voltage		> 5 mV		5 min.
Balancing cell voltage		>= 3805 mV		5 min.
Battery pack current		current within ±5% battery		5 min.
		capacity		

# **11.2.7** Deviation voltages and temperatures

Table 29 Deviation voltage and temperature boundary limits slave BMS

		Boundary condition		
Name	Level	Economic	Performance	Time
Deviation cell voltage	Set	<ul> <li>Difference highest and lowest cell voltage &gt;= 300 mV;</li> <li>Iowest cell voltage &gt;= 3325;</li> <li>current within ±5% battery capacity</li> </ul>		4-6 min.
	Clear	<ul> <li>Difference highest a voltage &lt; 240 mV;</li> <li>lowest cell voltage &gt; current within ±5% b</li> </ul>	4-6 min.	
Deviation cell temperature	Set	Difference highest temperature		4-6 min.
	Clear	Difference highest temperature		4-6 min.



# **12 TECHNICAL SPECIFICATIONS**

The technical specifications of this product can be downloaded from the MG Download Center.

https://downloads.mgenergysystems.eu/he/documents/technical-specification-en

# **13 DIMENSIONS**

The dimensions of this product can be downloaded from the MG Download Center.

https://downloads.mgenergysystems.eu/he/drawings



# **14 CONTACT DETAILS**

For specific questions please feel free to contact us.



**MG Energy Systems B.V.** Foeke Sjoerdswei 3 NL-8914 BH Leeuwarden The Netherlands

For support contact your local dealer:

https://www.mgenergysystems.eu/dealers/